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The syntax needed to be typed is the line following "In[]=" . The term is used here to more accurately demonstrate coding in Mathematica. To find a general solution of the linear system of ordinary differential equation: $\left[\begin{array}{l} \frac{dx}{dt} = 4x + 8y \\ \frac{dy}{dt} = 10x + 2y \end{array} \right]$ We first put the system in matrix form: $A = \left[\begin{array}{l} \end{array} \right]$

~~40.4: Using eigenvalues and eigenvectors to find stability ...~~

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2044 CHAPTER 2. DYNAMIC MODELS Solution: (a) Rotor: $J_1 \dot{\theta}_1 = B_{11} \theta_1 + T_m$
Load: $J_2 \dot{\theta}_2 = b_{21} \theta_1 + T_m$ Circuit: $v_a - K_e \omega = L_a \frac{d i_a}{dt} + R_a i_a$ Relation between the output torque and the armature current: $T_m = K_t i_a$ 46. 2045 23.

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Linear dynamical systems are dynamical systems whose evaluation functions are linear. While dynamical systems, in general, do not have closed-form solutions, linear dynamical systems can be solved exactly, and they have a rich set of mathematical properties. Linear systems can also be used to understand the qualitative behavior of general dynamical systems, by calculating the equilibrium points ...

~~Linear dynamical system—Wikipedia~~

Lorenz discovered that solutions of (1.2) may behave chaotically, showing that even low-dimensional nonlinear dynamical systems can behave in complex ways. Solutions of chaotic systems are sensitive to small changes in the initial conditions, and Lorenz used this model to discuss the unpredictability of weather (the "butterfly effect").

~~Introduction to Dynamical Systems John K. Hunter~~

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Maps. A discrete-time, affine dynamical system has the form of a matrix difference equation: $x_{k+1} = A x_k + B u_k$, with

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A a matrix and b a vector. As in the continuous case, the change of coordinates $x = x + (1 - A) - 1 b$ removes the term b from the equation. In the new coordinate system, the origin is a fixed point of the map and the solutions are of the linear system $A^n x = 0$.

~~Dynamical system - Wikipedia~~

DYNAMIC MODELS Fig. 2.44 Mechanical system for Problem 2.2 Solution: The key is to draw the Free Body Diagram (FBD) in order to keep the signs right. To identify the direction of the spring forces...

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7 Analytical Solution of Linear Dynamic Systems 197. 7.1 Introduction 197. 7.2 Analytical Solutions to Linear Differential Equations 197. 7.3 First-Order System Response 205. 7.4 Second-Order System Response 213. 7.5 Higher-Order Systems 230. 7.6 State-Space Representation and Eigenvalues 232. 7.7 Approximate Models 235. Summary 237. Reference ...

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